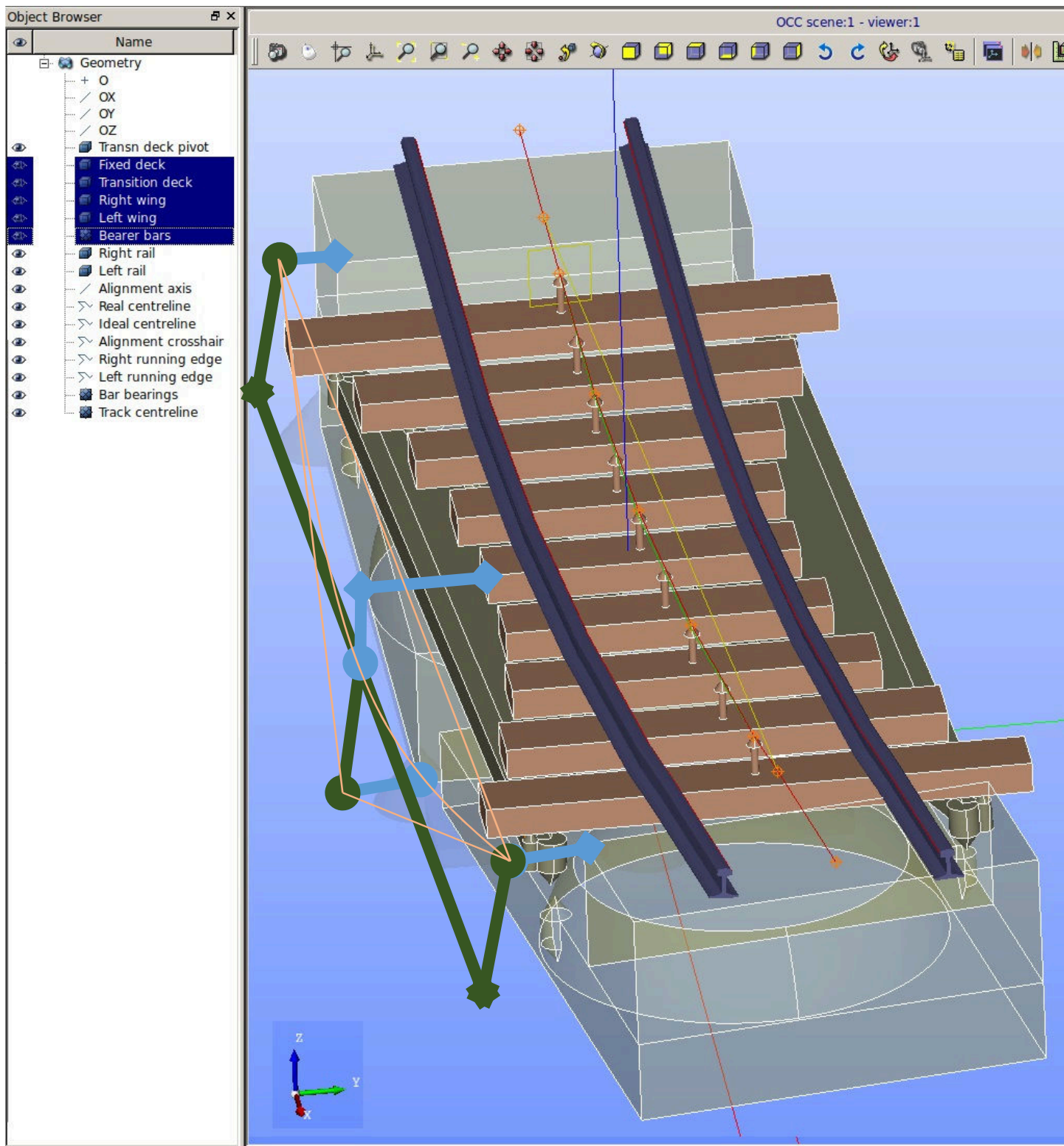


Schematic arrangement of lateral (yaw) CESuRa device



```
Python Console
>>> import c3d062a
found aflA.py ... found p56E1sketch.wr3k ... found c3d-demo2.ini ... found c3d-demo2.txt ... found c3d062a.py ... .. done
Input parameters: Lw Hb Lc Lp Hc Ww Wp Gw wo wf => 5000.0 600.0 300.0 400.0 300.0 800.0 0.001 2000.0 -100.0 0.7
Bearers => 9 Angles of pitch, roll and yaw => 2.0 0.001 8.0
designing joint ... done ... saved as c3dout-150505-demo2.csv
building joint ... done ... positioning components ... done ... extruding rails ... finished
>>>
```

